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## **TC 3700 Inventor Search Program**

See attached inventor searches for applications and/or patents to help resolve questions of overlapping subject matter. These searches are provided as an initial examination aid: examiners should perform updated or expanded PALM or EAST inventors searches as appropriate.

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**Serial Number:**    10 | 736,031

**1.) See attached printout of inventors listed in  
PALM**

**2.) See attached EAST Inventor Search  
Printout shows Inventor search terms**

US 20040260481 A1	20041223	Method for monitoring a machine and such a machine, particularly a robot	702/33		Heiligensetzer, Peter et al.
US 20040143951 A1	20040729	Method and device for positioning components to be joined together	29/428		Berninger, Alwin
US 20020130513 A1	20020919	Wearing ring	285/45		Berninger, Alwin et al.
US 20010023767 A1	20010927	Highly flexible hose end piece	174/48		Berninger, Alwin et al.
US 20010022112 A1	20010920	Device for compensating the weight of a robot arm	74/490.01		Bayer, Albert et al.
US 6761189 B2	20040713	Wearing ring	138/157	138/104; 138/108; 138/110; 138/161; 384/273	Berninger; Alwin et al.
US 6622756 B2	20030923	Highly flexible hose end piece	138/121	138/109; 138/120	Berninger; Alwin et al.
US 6564667 B2	20030520	Device for compensating the weight of a robot arm	74/490.01	267/291; 901/48	Bayer; Albert et al.
US 6352369 B1	20020305	Wearing ring for a cable guidance tube of a robot	384/273	384/297; 384/448	Berninger; Alwin
US 6288512 B1	20010911	Robot with cables extending at least partially on an outside	318/568.1	191/12R; 318/568.11; 318/568.12; 414/680; 414/730; 414/918	Berninger; Alwin et al.

US 6223618 B1	20010501	Device for driving a robot hand	74/490.06	901/29	Berninger; Alwin et al.
US 6189403 B1	20010220	Robot arm	74/490.02	414/918; 901/50	Berninger; Alwin